

From Autonomous to Nonautonomous Difference Equations: NEW CHALLENGES

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Autonomous Difference Equations/Maps

A given map $f : X \rightarrow X$, where X is a metric space or just \mathbb{R}^n , is associated with the difference equation

$$x_{n+1} = f(x_n). \quad (1)$$

For $x_0 \in X$, $x_n = f^n(x_0)$, $f^n = f \circ f^{n-1}, \dots, f^2 = f \circ f$.

So one speaks of the orbit of x_0 under the map f as the set

$$O(x_0) = \{x_0, f(x_0), \dots, f^n(x_0), \dots\},$$

or equivalently

$$O(x_0) = \{x_0, x_1, \dots, x_n, \dots\}.$$

A point x^* is fixed if $f(x^*) = x^*$; it is of period r if $f^r(x^*) = x^*$.

Similarly, a map $f : X \times X \rightarrow X$, gives rise to the difference equation

$$x_{n+1} = f(x_n, x_{n-1}) \quad (2)$$

and so on.

The Fundamental Theorem of First Order Difference Equation (Sharkovsky Theorem)

Let us order the set of natural numbers $\mathbb{N} \cup \{2^\infty\} = \mathbb{N}^*$ as follows.

$$\begin{aligned} & 3 \triangleright 5 \triangleright 7 \triangleright \dots \\ & 2 \times 3 \triangleright 2 \times 5 \triangleright 2 \times 7 \triangleright \dots \\ & \vdots \\ & 2^n \times 3 \triangleright 2^n \times 5 \triangleright 2^n \times 7 \triangleright \dots \\ & \vdots \\ & 2^\infty \triangleright \dots \triangleright 2^n \triangleright \dots \triangleright 2 \triangleright 1 \end{aligned}$$

Theorem 1 (Sharkovsky) *Let $f : I \rightarrow I$ be a continuous map on a closed interval $I \subseteq \mathbb{R}$. If the equation $x_{n+1} = f(x_n)$ has a cycle of minimal period r , then it has also cycles of the minimal period s for all $r \triangleright s$.*

Open Problem 1 Extend Sharkovsky's Theorem to the equation

$$x_n = f(x_{n-2})$$

and more generally to

$$x_n = f(x_{n-k}).$$

Let $q \in \mathbb{N}^*$. Define

$$S_k(q) = \begin{cases} \{1\} & \text{if } q = 1, \\ \{l \cdot q : l|k \text{ and } \gcd(\frac{k}{l}, q) = 1\} & \text{if } q \in \mathbb{N} \setminus \{1\}, \\ \{l : l \geq 2 \text{ and } l|k\} & \text{if } q = 2^\infty. \end{cases}$$

Definition 2 Let $k \in \mathbb{N}$. The k -Sharkovsky order is given by

$$\begin{aligned} S_k(3) \triangleright S_k(5) \triangleright \dots \triangleright S_k(2 \cdot 3) \triangleright \dots \\ \triangleright \dots \triangleright S_k(2^2) \triangleright S_k(2) \triangleright S_k(1). \end{aligned}$$

Example 3 Let $k = 2$. Then

$$\begin{aligned} S_2(3) &= \{3, 2 \cdot 3\} \\ S_2(2^m \cdot 3) &= \{2^{m+1} \cdot 3\} \\ \{3, 2 \cdot 3\} &\triangleright \{5, 2 \cdot 5\} \triangleright \dots \\ 2^2 \cdot 3 &\triangleright 2^2 \cdot 5 \triangleright \dots \\ &\vdots \\ \dots &\triangleright 2^{m+1} \triangleright \dots \triangleright 2^2 \triangleright 1. \end{aligned}$$

Open Problem 2 Let $f : I \rightarrow I$ be a continuous function on I . Prove that if the difference equation

$$x_n = f(x_{n-1}) \quad (3)$$

has a cycle of minimal period r , then the difference equation

$$x_n = f(x_{n-k}) \quad (4)$$

has cycles of period q for all numbers $q \in S_k(m)$, whenever $S_k(r) \supseteq S_k(q)$. Moreover, if f has more than one fixed point, then equation (4) has cycles of minimal periods q for all $q \in S_k(2^\infty)$.

* A nice trick.

Let

$$y_1(n) = x_{nk-1}, y_2(n) = x_{nk-2}, \dots, y_k(n) = x_{nk-k}.$$

Then

$$\begin{aligned} y_1(n+1) &= f(y_1(n)), y_2(n+1) = f(y_2(n)), \\ &\dots, y_k(n+1) = f(y_k(n)). \end{aligned}$$

Open Problem 3 (Ladas) Let $f : I \rightarrow I$ be a continuous map and suppose that every orbit (solution) of the equation $x_{n+1} = f(x_n)$ is of minimal period r . Show that either $r = 1$ or $r = 2$.

Is this extendable to

- $x_{n+1} = f(x_n, x_{n-1})$?
- $x_{n+1} = f(x_{n-k})$?

Nonautonomous Difference Equations: The Periodic Case

Motivation: The following model (Beverton-Holt) is used to model fish such as salmon.

$$x_{n+1} = \frac{\mu K x_n}{K + (\mu - 1)x_n}, \quad (5)$$

where μ is the intrinsic growth rate of the population, and K is its carrying capacity. This is a simple monotonic model and it is known that if $K > 0$, $\mu > 1$, the equation has a positive fixed point $x^* = K$ which is globally asymptotically stable on $(0, \infty)$.

Cushing and Henson suggested nonautonomizing (5) by letting K to vary periodically, i.e, $K_{n+p} = K_n$, for all $n \in \mathbb{Z}^+$. Hence, we have the following nonautonomous difference equation.

$$x_{n+1} = \frac{\mu K_n x_n}{K_n + (\mu - 1)x_n} \quad (6)$$

Open Problem 4 Show that if $\mu > 1$ and $K_n > 0$, equation (6) has a periodic solution (of minimal period p) which is globally asymptotically stable on $(0, \infty)$.

Open Problem 5 Let $\{\bar{x}_0, \bar{x}_1, \dots, \bar{x}_{p-1}\}$ be the periodic orbit of equation (6). Show that

$$\frac{1}{p} \sum_{i=0}^{p-1} x_i < \frac{1}{p} \sum_{i=0}^{p-1} K_i, \quad p \geq 2.$$

Open Problem 6 Extend problems 4 and 5 to

$$(a) \quad x_{n+1} = \frac{\mu_n K_n x_n}{K_n + (\mu_n - 1)x_n},$$

$$(b) \quad x_{n+1} = \frac{\mu K_n x_{n-k}}{K_n + (\mu - 1)x_{n-k}},$$

$$(c) \quad x_{n+1} = \frac{\mu K_n x_{n-t}}{K_n + (\mu - 1)x_{n-s}},$$

The setup: Why skew-product dynamical system?

What is a dynamical system?

Let X be a metric space (\mathbb{R}^n as an example), and T a topological group (topological semigroup). Then $\pi : X \times T \rightarrow X$ is called a dynamical system or (X, T, π) is a dynamical system if

- (i) π is continuous,
- (ii) $\pi(x, 0) = x$ for all $x \in X$,
- (iii) $\pi(\pi(x, s), t) = \pi(x, s + t)$ (the associative property or the group property).

Important Examples

1. $T = \mathbb{R}^+(\mathbb{R})$: differential equations
2. $T = \mathbb{Z}^+(\mathbb{Z})$: difference equations
3. $T = h\mathbb{Z}^+$, $h \in \mathbb{R}$

Example 4 $T = \mathbb{Z}^+$. We let $\pi(x_0, n) = f^n(x_0)$. Hence every difference equation

$$x_{n+1} = f(x_n)$$

with continuous f generates a dynamical system.

Example 5 Consider the nonautonomous difference equation

$$x_{n+1} = (-1)^n \left(1 + \frac{1}{n+1} \right) x_n, \quad n \in \mathbb{Z}^+.$$

Then $x_n = (-1)^{\frac{n(n-1)}{2}} (n+1)x_0$. If we let $\pi(x_0, n) = x_n$. Then

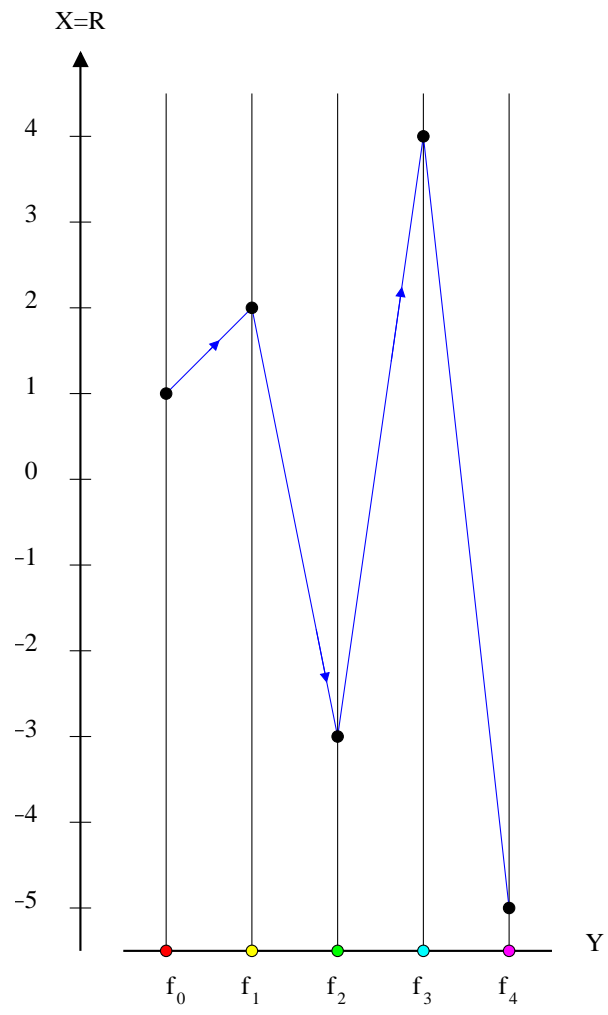
$$\pi(\pi(x_0, s), t) = (-1)^{\frac{t(t-1)}{2}} (-1)^{\frac{s(s-1)}{2}} (t+1)(s+1)x_0$$

while

$$\begin{aligned} \pi(x_0, s+t) &= (-1)^{\frac{(s+t)(s+t-1)}{2}} (s+t+1)x_0 \\ &\neq \pi(\pi(x_0, s), t) \end{aligned}$$

To remedy this situation, let $Y = \{f_0, f_1, f_2, \dots\}$, where $f_i(x) = (-1)^i \left(1 + \frac{1}{i+1} \right) x$. Let $X = \mathbb{R} \times Y$ and define $\pi : X \times \mathbb{Z}^+ \rightarrow X$ as $\pi((x, f_i), n) = (f_{i+n-1} \cdots \circ f_{i+1} \circ f_i(x), f_{i+n})$. Then $\pi(\pi((x, f_i), s), t) = \pi((x, f_i), s+t)$ and π is a dynamical system.

$$\begin{array}{ccc} \mathbb{R} \times Y \times \mathbb{Z}^+ & \xrightarrow{\pi} & \mathbb{R} \times Y \\ \downarrow p \times id & & \downarrow \phi p(x, f_i) = f_i \\ Y \times \mathbb{Z}^+ & \xrightarrow{\sigma} & Y \\ \sigma(f_i, n) & = & f_{i+n} \end{array}$$



Periodic difference equations

$$x_{n+1} = f_n(x_n), \quad f_{n+p} = f_n \quad \text{for all } n \in \mathbb{Z}^+$$

A geometric r -cycle is a set of points

$$c_r = \{\bar{x}_0, \bar{x}_1, \dots, \bar{x}_{r-1}\}$$

such that

$$f_{(i+nr) \bmod p}(\bar{x}_i) = \bar{x}_{(i+1) \bmod r}.$$

A complete r -cycle in the skew-product system generated by c_r is the set

$$c_r = \{(x_0, f_0), (x_1, f_1), \dots, (x_{s \bmod r}, f_{s \bmod p})\}$$

where $s = \text{lcm}[r, p]$.

For $r = 4$, $p = 6$ we have the following diagram.

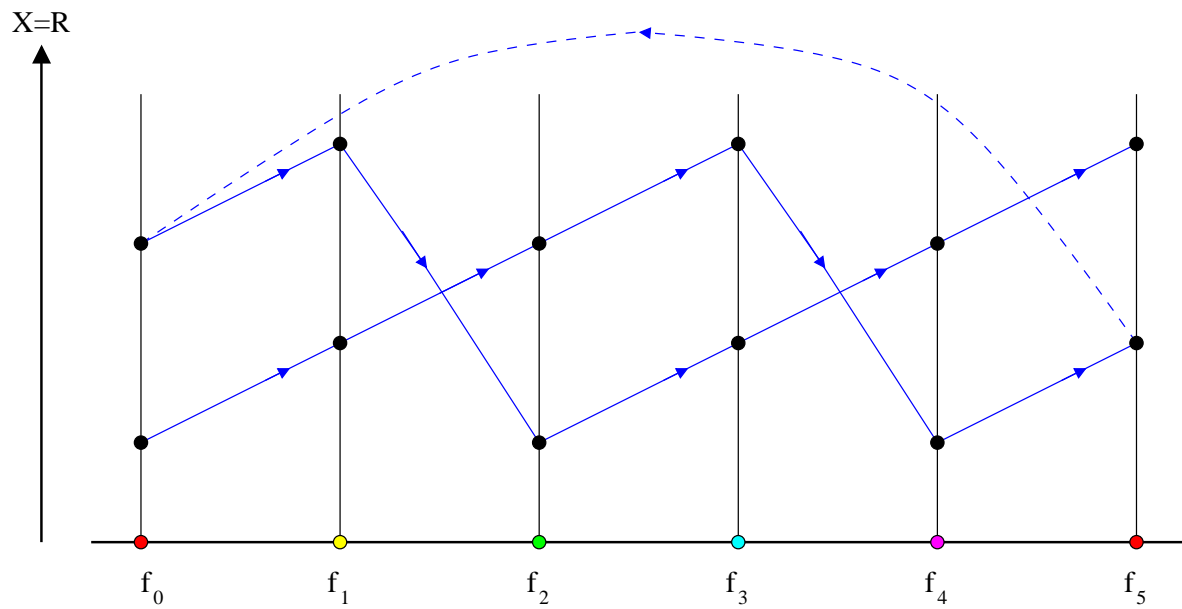


Figure 1: A geometric 4-cycle and a complete 12-cycle.

Remarks 6 *Prove the following statements.*

- (i) *The complete cycle has period $s = \text{lcm}[r, p]$.*
- (ii) *Each fiber $\mathcal{F}_i = p^{-1}(f_i)$, $1 \leq i \leq p$, contains $l = \frac{s}{p}$ elements.*
- (iii) *The maps $f_0, f_d, f_{2d}, \dots, f_{(m-1)d}$ intersect at the points $(\bar{x}_0, \bar{x}_1), (\bar{x}_d, \bar{x}_{d+1}), \dots, (\bar{x}_{(m-1)d \bmod r}, \bar{x}_{(m-1)d+1 \bmod r})$.*
- (iv) *Use (iii) to show that it is possible that the p -periodic Beverton Hold equation*

$$x_{n+1} = \frac{\mu_n K_n x_n}{K_n + (\mu_n - 1)x_n}, \quad \mu_n > 1, \quad K_n > 0$$

may have periodic solutions (orbits) of period $r < p$.

Open Problem 7 Let $f_n : X \rightarrow X$, $f_{n+p} = f_n$ for all $n \in \mathbb{Z}^+$, be continuous maps on a connected metric space X . Show that if $c_r = \{\bar{x}_0, \bar{x}_1, \dots, \bar{x}_{r-1}\}$ is globally asymptotically stable geometric cycle of $x_{n+1} = f_n(x_n)$, then r must divide p .

Corollary 7 *If $f_n = f$ for all n , that is $p = 1$, then $r = 1$. In other words, there are no globally asymptotically periodic cycles of period $r > 1$ in a connected metric space.*

Open Problem 8

(i) Prove Corollary 7.

(ii) Suppose that $f : X \rightarrow X$, $X = \bigcup_{i=1}^k M_i$, where each M_i is a connected component in the metric space X . If a periodic orbit of period r is globally asymptotically stable, prove the $r \leq k$.

Open Problem 9 Extend to difference equations with delay in the form

(a) $x_{n+1} = f_{n-1}(x_{n-k})$

(b) $x_{n+1} = f_n(x_n, x_{n-1})$

(c) $x_{n+1} = f_n(x_n, x_{n-k}), k \neq 1$

(d) $x_{n+1} = f_n(x_n, x_{n-1}, \dots, x_0)$